

Necessary and sufficient conditions for sufficiency

The necessary and sufficient condition for an estimator to be sufficient for a parameter is provided by the factorization theorem due to Neyman is as follows:-

The estimator $T = t(x_1, x_2, \dots, x_n)$ is sufficient for θ if and only if the joint p.d.f. L (say) of the sample values can be expressed in the form

$$L = g_\theta[t(x)] \cdot h(x)$$

where $g_\theta[t(x)]$ depends on θ and x only through the value of $t(x)$ and $h(x)$ is independent of θ .

Proof:

Necessary condition

Let the statistic T_1 be sufficient for the parameter θ . If we consider any additional $(n-1)$ statistics T_2, T_3, \dots, T_n which are algebraically unrelated to T_1 , then the conditional distribution of T_2, T_3, \dots, T_n for given $T_1 = t_1$ must be independent of θ . Hence the joint p.d.f. of T_1, T_2, \dots, T_n will be of the form.

$$\Phi_\theta(t_1, t_2, \dots, t_n) = g_\theta(t_1) h_1(t_2, t_3, \dots, t_n / t_1)$$

where $g_\theta(t_1)$ is the marginal p.d.f. of T_1 and $h_1(t_2, t_3, \dots, t_n / t_1)$ is the conditional p.d.f. of T_2, T_3, \dots, T_n given $T_1 = t_1$.

Now let us consider the one to one transformation.

$$(t_1, t_2, \dots, t_n) \rightarrow (x_1, x_2, \dots, x_n)$$

Hence the joint p.d.f. of x_1, x_2, \dots, x_n is

$$f_\theta(x_1, x_2, \dots, x_n) = \Phi_\theta[t_1(x_1, x_2, \dots, x_n), \dots, t_n(x_1, x_2, \dots, x_n)] \times \left| J \left(\frac{t_1, \dots, t_n}{x_1, x_2, \dots, x_n} \right) \right|$$

$$\begin{aligned} \rightarrow f_0(x_1, x_2, \dots, x_n) &= g_0(t_1, t_2, \dots, t_n) \cdot h(x_1, x_2, \dots, x_n), \dots \\ &= g_0(t_1) h(x_1, x_2, \dots, x_n), \text{ (say)} \end{aligned}$$

where $g_0(t_1) = g_0(t_1, t_2, \dots, t_n)$

and $h(x_1, x_2, \dots, x_n) = h_1(t_1, t_2, \dots, t_n) \times \left| J \left(\frac{t_1, t_2, \dots, t_n}{x_1, x_2, \dots, x_n} \right) \right|$

Thus the necessary condition of factorization theorem is established.

Sufficient condition

Suppose the factorization criterion holds. Then we have

$$f_0(x_1, x_2, \dots, x_n) = g_0(t_1) h(x_1, x_2, \dots, x_n).$$

Now let us consider the one to one transformation

$$(x_1, x_2, \dots, x_n) \longrightarrow (t_1, t_2, \dots, t_n).$$

Hence the joint p.d.f of T_1, T_2, \dots, T_n is

$$\begin{aligned} f_0(t_1, t_2, \dots, t_n) &= f_0[x_1(t_1, t_2, \dots, t_n), x_2(t_1, t_2, \dots, t_n), \dots, x_n(t_1, t_2, \dots, t_n)] \\ &\quad \times \left| J \left(\frac{x_1, x_2, \dots, x_n}{t_1, t_2, \dots, t_n} \right) \right| \end{aligned}$$

$$= g_0(t_1) \times h[x_1(t_1, t_2, \dots, t_n), \dots, x_n(t_1, t_2, \dots, t_n)]$$

$$\times \left| J \left(\frac{x_1, x_2, \dots, x_n}{t_1, t_2, \dots, t_n} \right) \right|$$

$$= g_0(t_1) \times C(t_1, t_2, \dots, t_n)$$

where $C(t_1, t_2, \dots, t_n) = h[x_1(t_1, t_2, \dots, t_n), \dots, x_n(t_1, t_2, \dots, t_n)]$

$$\times \left| J \left(\frac{x_1, x_2, \dots, x_n}{t_1, t_2, \dots, t_n} \right) \right|$$

Now the marginal p.d.f of T is obtained from this joint p.d.f of t_1, t_2, \dots, t_n by integrating out t_2, t_3, \dots, t_n and hence is of the form.

$$g_0(t_1) \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} C(t_1, t_2, \dots, t_n) \prod_{i=2}^n dt_i$$

$$= g_0(t_1) K(t_1).$$

Hence the conditional p.d.f of T_2, T_3, \dots, T_n given $T_1 = t_1$ is

$$= C(t_1, t_2, \dots, t_n) / K(t_1).$$

which is independent of θ .

Hence the sufficient condition is established.